

CONTROL ENGINEERING AND APPLIED INFORMATICS JOURNAL

DECLARATION

I hereby certify that the paper entitled “**Sequential Covariance-weighted Quasiconvex solution to Mapping in Visual SLAM**”, written by the author **A. H. Abdul Hafez** presents the original results of my research activity. We warrant that the above work has not been previously published elsewhere.

April 3, 2014

Date



Original signature of the first author

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