

CONTROL ENGINEERING AND APPLIED INFORMATICS JOURNAL

DECLARATION

I hereby certify that the paper entitled **Control of a hydraulic servo system using sliding mode with an integral and realizable reference compensation.**

written by the authors *Emna Kolsi-Gdoura, Moez Feki and Nabil Derbel*.....

.....
presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

_ Date 02/04/2014 _

Original signature of the first author

A handwritten signature in blue ink, reading "Emna Kolsi", with a stylized flourish at the end.

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