

## Declaration of Originality

I, Mr. /Mrs. /Ms. \_\_\_\_\_ **Mustapha \_LITIM** \_\_\_\_\_, with ID number  
2747 \_\_\_\_\_, and work affiliation \_\_PhD, Student\_\_ in Automatic and Control \_\_\_\_\_  
in \_\_\_\_\_ University of Sciences and Technology USTO-MB, Faculty of Electrical Engineering,  
Automatic Control Department, LDEE Laboratory, BP 1505 Oran El M'Naouer, Algeria. \_\_\_\_\_

### CERTIFY:

That I am the author of the article entitled:

**Control of 2dof Planar Parallel Manipulator Using Backstepping Approach** \_\_\_\_\_, and

that this article has not been published previously nor is it under review for publication in  
any other journal at this time. Therefore, I formally solicit its publication in the Journal of  
Control Engineering and Applied Informatics.

For all effects,

The Author/s

Mustapha Litim

Sign

Date: 09/8/2014

A handwritten signature in blue ink, appearing to be 'ML' or similar, written over a horizontal line.