

CONTROL ENGINEERING AND APPLIED INFORMATICS JOURNAL

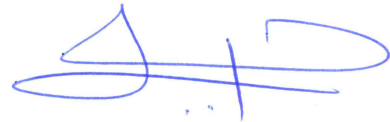
DECLARATION

I hereby certify that the paper entitled **...Adaptive RBFNN-HOMS Nonsingular Terminal Sliding Control of n-DOF Robotic Manipulator.....**
written by the authors **...Amar REZOUG, Bertrand TONDU, Mustapha HAMERLAIN and Mohamed TADJINE.....**
presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

Tuesday, February 5th, 2015
Date

Original signature of the first author

A. REZOUG



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