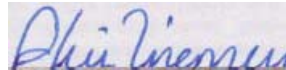


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DECLARATION

I hereby certify that the paper entitled “Design of a global extremum seeking algorithm for an omni-directional robot model” written by the author Erkin Dincmen presents the original results of my research activity. I warrant that the above work has not been previously published elsewhere.

May, 04, 2016
Date



Original signature of the first author

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