

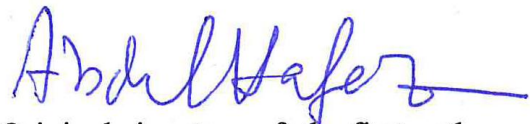
CONTROL ENGINEERING AND APPLIED INFORMATICS JOURNAL

DECLARATION

I hereby certify that the paper entitled “**Reliable 2D Tracking using good texture and edge features for Robotic Vision**”, written by the authors **A. H. Abdul Hafez** and **Visesh Chari**, presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

May 23, 2016

Date



Original signature of the first author

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