

CONTROL ENGINEERING AND APPLIED INFORMATICS JOURNAL

DECLARATION

I hereby certify that the paper entitled Adaptive Fuzzy-PD Tracking Controller for Optimal Visual-Servoing of Wheeled Mobile Robots written by the authors Omer Saleem, Humble Hassan, Awais Khan, Usman Javaid presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

9th September, 2016
Date



9/9/16

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