

# CONTROL ENGINEERING AND APPLIED INFORMATICS JOURNAL

## DECLARATION

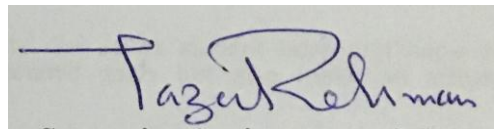
I hereby certify that the paper entitled

**Synchronization of A Novel 4-D Hyperchaotic Rikitake Dynamo System With Unknown Parameters Via Adaptive Integral Sliding Mode**

written by the authors **Fazal ur Rehman, Sami ud Din** presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

26<sup>th</sup> Sept 2016

Date

A photograph of a handwritten signature in blue ink on a light-colored surface. The signature is written in a cursive style and appears to read 'Fazal Rehman'.

Original signature of the first author

On completion, please upload the original form on the site <http://ceai.srait.ro>  
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