

CONTROL ENGINEERING AND APPLIED INFORMATICS JOURNAL

DECLARATION

I hereby certify that the paper entitled*Autonomous Underwater Vehicle Robust Path Tracking: Generalized Super-Twisting Algorithm and Block Backstepping Controllers* written by the authors ...*Jesus Guerrero Tavares, Jorge A. Torres Muñoz, Elba Antonio Yañez and Eduardo Campos Mercado*... presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

June 23, 2017
Date


Original signature of the first author

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