

CONTROL ENGINEERING AND APPLIED INFORMATICS JOURNAL

DECLARATION

I hereby certify that the paper entitled **Fault Detection and Isolation for Manipulator Robot Using Optimal Unknown Input Observer** written by the authors S. M. Hosseinpour Moshgani. A. Fakharian, presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

____5 October____ , 2017____
Date

Original signature of the first author



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