

CONTROL ENGINEERING AND APPLIED INFORMATICS JOURNAL

DECLARATION

I hereby certify that the paper entitled**Adaptive output feedback force tracking control for Lower Extremity Power-assisted Exoskeleton**..... written by the authorsShengli Song, Xinglong Zhang, Haitao Wang, Jinhong Xue, Yuxuan Cao, Junyong Fu, Fangwen Tu..... presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

_____19/02_____, 2018_____
Date

Original signature of the first author

Shengli Song

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