

CONTROL ENGINEERING AND APPLIED INFORMATICS JOURNAL

DECLARATION

I hereby certify that the paper entitledRobust H_∞ Fault-Tolerant Control for Dynamic Positioning Ship Based on Sampled-data.....
written by the authorsShenhua Yang, Minjie Zheng.....

.....
presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

21st March, 2018

Date



Original signature of the first author

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