

CONTROL ENGINEERING AND APPLIED INFORMATICS JOURNAL

DECLARATION

I hereby certify that the paper entitled Genetic-Algorithm based Inverse Gain-Scheduling of PID Controller-Gains for Posture-Stabilization of Self-Balancing-Robots under Depleting Battery Conditions written by the authors Omer Saleem, Mohsin Rizwan, Panos S. Shiokolas, Babar Ali presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

10 October 2018

Date



Original signature of the first author

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