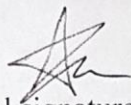


CONTROL ENGINEERING AND APPLIED INFORMATICS JOURNAL

DECLARATION

I hereby certify that the paper entitled "Robust backstepping control for highly demanding quadrotor flight", written by the authors Manuel Alejandro Vallejo-Alarcon, Martín Velasco-Villa, and Rafael Castro-Linares, presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

February 7, 2019
Date



Original signature of the first author

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