

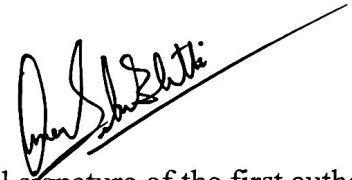
CONTROL ENGINEERING AND APPLIED INFORMATICS JOURNAL

DECLARATION

I hereby certify that the paper entitled Self-Tuning State-Feedback Control of Rotary Pendulum via Online Adaptive Reconfiguration of Control Penalty-Factor written by the authors Omer Saleem, Khalid Mahmood-ul-Hasan, Mohsin Rizwan presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

6th May 2020

Date



Original signature of the first author

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