

CONTROL ENGINEERING AND APPLIED INFORMATICS JOURNAL

DECLARATION

I hereby certify that the paper entitled “A Passivity-based Decomposing Method for Operational Space Control of Kinematical Redundant Tele-operation Systems” written by the authors Kamil Cetin and Enver Tatlicioglu presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

August 13, 2020

Kamil Cetin

A handwritten signature in black ink, appearing to be 'Kamil Cetin', with a large, stylized initial 'K' and a series of loops and strokes that form the rest of the name.

On completion, please upload the original form on the site <http://ceai.srait.ro>
Control Engineering and Applied Informatics Journal