

CONTROL ENGINEERING AND APPLIED INFORMATICS JOURNAL

DECLARATION

I hereby certify that the paper entitled "Superposition modeling method of inverted pendulum considering Coulomb friction based on Lagrange equation and its model predictive control" written by the authors Jianwei Wu, Beibei Sun, Rui Huang and Zhao Peng presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

September 5, 2020
Date

Original signature of the first author

Jianwei Wu

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