

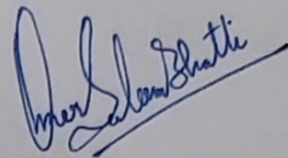
CONTROL ENGINEERING AND APPLIED INFORMATICS JOURNAL

DECLARATION

I hereby certify that the paper entitled Self-Adaptive Stabilization Control of a Rotary Pendulum using Nonlinearly-Scaled Model-Reference Gain-Adaptation Law written by the authors Omer Saleem, Fahim Gohar Awan, Samia Mahmood, Sheroze Liaquat, Hamza Yousuf presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

23/01/2021

Date



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