

CONTROL ENGINEERING AND APPLIED INFORMATICS JOURNAL

DECLARATION

I hereby certify that the paper entitled *Improved BP network based sliding model tracking control for a quadrotor UAV* written by the authors Qiang-wei Pang, De-shi Wang, Wei Wu, Ye Chen, Yong-yong Zhu presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

Monday, June 07, 2021

Original signature of the first author

Qiang-wei pang