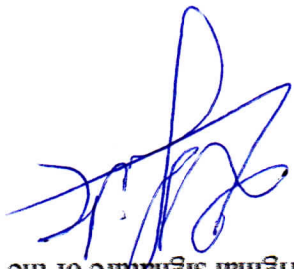


DECLARATION

I hereby certify that the paper entitled: Optimal ANFIS-FOPID with back-stepping Controller design for wheeled Mobile Robot control
Written by the authors: R. EULDI, N. Batel, R. Rebhi, M r. SKENDER.
Presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

14/02, 2022
Date

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