

DECLARATION

I hereby certify that the paper entitled “LiDAR-Based Online Navigation Algorithm For An Autonomous Agricultural Robot” is a research report written by the authors Dang Nguyen Thanh, Hung Le Van and Luy Nguyen Tan. The authors declare no conflict of interest and no significant financial support for this work that could have influenced its outcome. Luy Nguyen and Hung Le gave the idea, managed and checked the paper, Dang Nguyen interpreted the results and wrote the paper. The whole document in the paper presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

Date: 11th March, 2022

Original signature of the first author

A handwritten signature in black ink, appearing to read 'Dang Nguyen Thanh', with a stylized, flowing script.

Dang Nguyen Thanh