

# CONTROL ENGINEERING AND APPLIED INFORMATICS JOURNAL

## DECLARATION

I hereby certify that the paper entitled *Stabilizing the Flexible Convergence of Swarm Robot by Fuzzy Attraction and Repulsion* written by the authors **Le Thi Thuy Nga**, **Nguyen Van Binh**, and **Le Hung Lan** presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

May 6, 2022  
Date

Original signature of the first author



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