

CONTROL ENGINEERING AND APPLIED INFORMATICS JOURNAL

DECLARATION

I hereby certify that the paper entitled *Fault Tolerant Attitude Estimation Strategy for a Quadrotor UAV under Total Sensor Failure* written by the authors *Boualem Nasri, Abdelrezak Guessoum, Akram Adnane, Lotfi Mostefai* presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

June 1st, 2022
Date

Original signature of the first author



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