

CONTROL ENGINEERING AND APPLIED INFORMATICS JOURNAL

DECLARATION

I hereby certify that the paper entitled “Enhancing Motion Planning for Industrial Robots Using Hybrid Methods and Quaternion Representation”

written by the authors AALHASAN ALI JOOD, SONG BAO presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

____Aug.-05____, 2024
Date



Original signature of the first author