

DECLARATION

I hereby certify that the paper entitled: "Enhancing Power Wheelchair Mobility with a Cost-Effective Vision-Only Deep Learning System for Obstacle Detection and Avoidance" written by the authors Abdul Hafis Abdulhafiz (A. H. Abdul Hafez) presents the original results of our research activity. We warrant that the above work has not been previously published elsewhere.

9/8/2025
Date


Original signature of the first author

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